Minutes team leader meeting 02.07.07

Teams attending the meeting
Ok Aros
Ok CAMBADA
Ok CoPS
Ok EIGEN
Ok Hibikino-Musashi
Ok ISocRob
Ok Mostly Harmless + AlmaniACs
Ok NuBot
Ok Orient+Trackies
Ok Tech. United
Ok Tribots

- Presentation of schedule for tomorrow
- Tribots agree to goalkeep with vips after opening ceremony
- Detailed steps for the challenge n. 5
  1. the robot is switched on (end of human interaction)
  2. the robot is carried by hand, and possibly with its vision system blinded, in a position in the field decided by the orgcomm
  3. from the refbox the orgcomm presses kickoff and then start
  4. this is repeated 3 times
  5. each team can use its own ball, provided it is a normal robocup midsize ball (nike or molten)
- Detailed steps for the challenge n. 4
  1. the robot is switched on (end of human interaction)
  2. the blue goal is the robot own goal (the robot has to score in the yellow goal)
  3. a ball is shown to the robot about 0.5m in front of the robot, for about 10s (robot is on the centre point of the field); for starting the “calibration period” the orgcomm presses kickoff from the refbox and 10s after stop is pressed
  4. the ball is carried by hand in a position in the field decided by the orgcomm (along the carpet junction in the yellow half-field, in front of each restart points along the central line)
  5. from the refbox the orgcomm presses kickoff and then start
  6. after the completion of the challenge (max 60s) the stop is pressed
  7. the process is repeated 3 times, each time changing the ball
- potential problem for packing on Friday afternoon: by 15:00 is not realistic
- network problem: usage of chann. 64 on 11a (Japanese teams cannot use that channel and the reconfiguring of the access point and devices just before a game is too risky => decision no usage of chann. 64 of 11a!
- Check amount of time available to teams for packing at the very end of the event.