

Minutes team leader meeting 02.07.07

Teams attending the meeting

Ok Aros

Ok CAMBADA

Ok CoPS

Ok EIGEN

Ok Hibikino-Musashi

Ok ISocRob

Ok Mostly Harmless + AlmaniACs

Ok NuBot

Ok Orient+Trackies

Ok Tech. United

Ok Tribots

- Presentation of schedule for tomorrow
- Tribots agree to goalkeep with vips after opening ceremony
- Detailed steps for the challenge n. 5
 1. the robot is switched on (end of human interaction)
 2. the robot is carried by hand, and possibly with its vision system blinded, in a position in the field decided by the orgcomm
 3. from the refbox the orgcomm presses *kickoff* and then *start*
 4. this is repeated 3 times
 5. each team can use its own ball, provided it is a normal robocup midsize ball (nike or molten)
- Detailed steps for the challenge n. 4
 1. the robot is switched on (end of human interaction)
 2. the blue goal is the robot own goal (the robot has to score in the yellow goal)
 3. a ball is shown to the robot about 0.5m in front of the robot, for about 10s (robot is on the centre point of the field); for starting the “calibration period” the orgcomm presses *kickoff* from the refbox and 10s after *stop* is pressed
 4. the ball is carried by hand in a position in the field decided by the orgcomm (along the carpet junction in the yellow half-field, in front of each restart points along the central line)
 5. from the refbox the orgcomm presses *kickoff* and then *start*
 6. after the completion of the challenge (max 60s) the *stop* is pressed
 7. the process is repeated 3 times, each time changing the ball
- potential problem for packing on Friday afternoon: by 15:00 is not realistic
- network problem: usage of chann. 64 on 11a (Japanese teams cannot use that channel and the reconfiguring of the access point and devices just before a game is too risky => decision no usage of chann. 64 of 11a!
- Check amount of time available to teams for packing at the very end of the event.